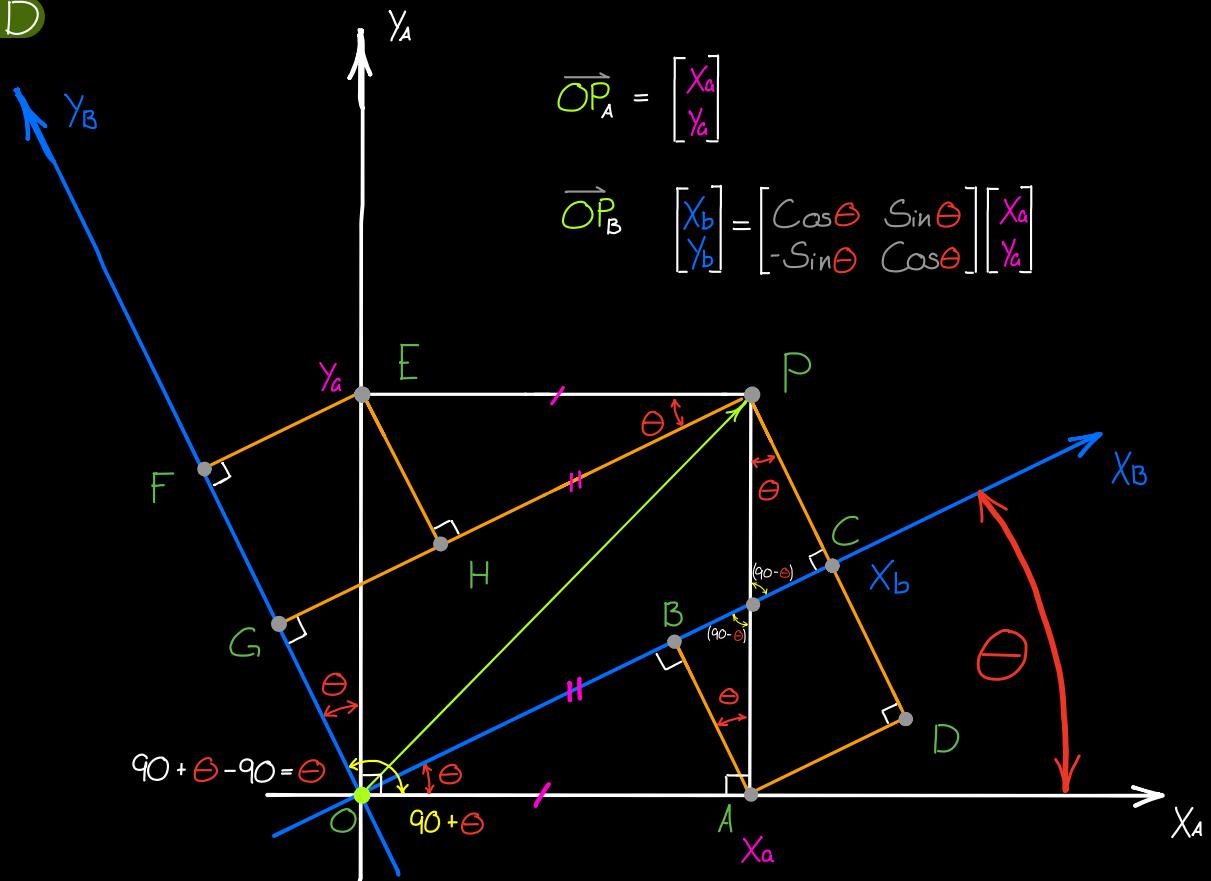


2D



$$\triangle OFE \rightarrow OF = OE \cos \theta \\ OF = Y_a \cos \theta$$

$$\triangle OBA \rightarrow OB = OA \cos \theta \\ OB = X_a \cos \theta$$

$$\downarrow FG = EH \downarrow$$

$$\downarrow BC = AD \downarrow$$

$$\triangle EPH \rightarrow EH = EP \sin \theta \\ FG = X_a \sin \theta$$

$$\triangle APD \rightarrow AD = AP \sin \theta \\ BC = Y_a \sin \theta$$

$$OG = OF - FG$$

$$OC = OB + BC$$

$$Y_b = Y_a \cos \theta - X_a \sin \theta$$

$$X_b = X_a \cos \theta + Y_a \sin \theta$$

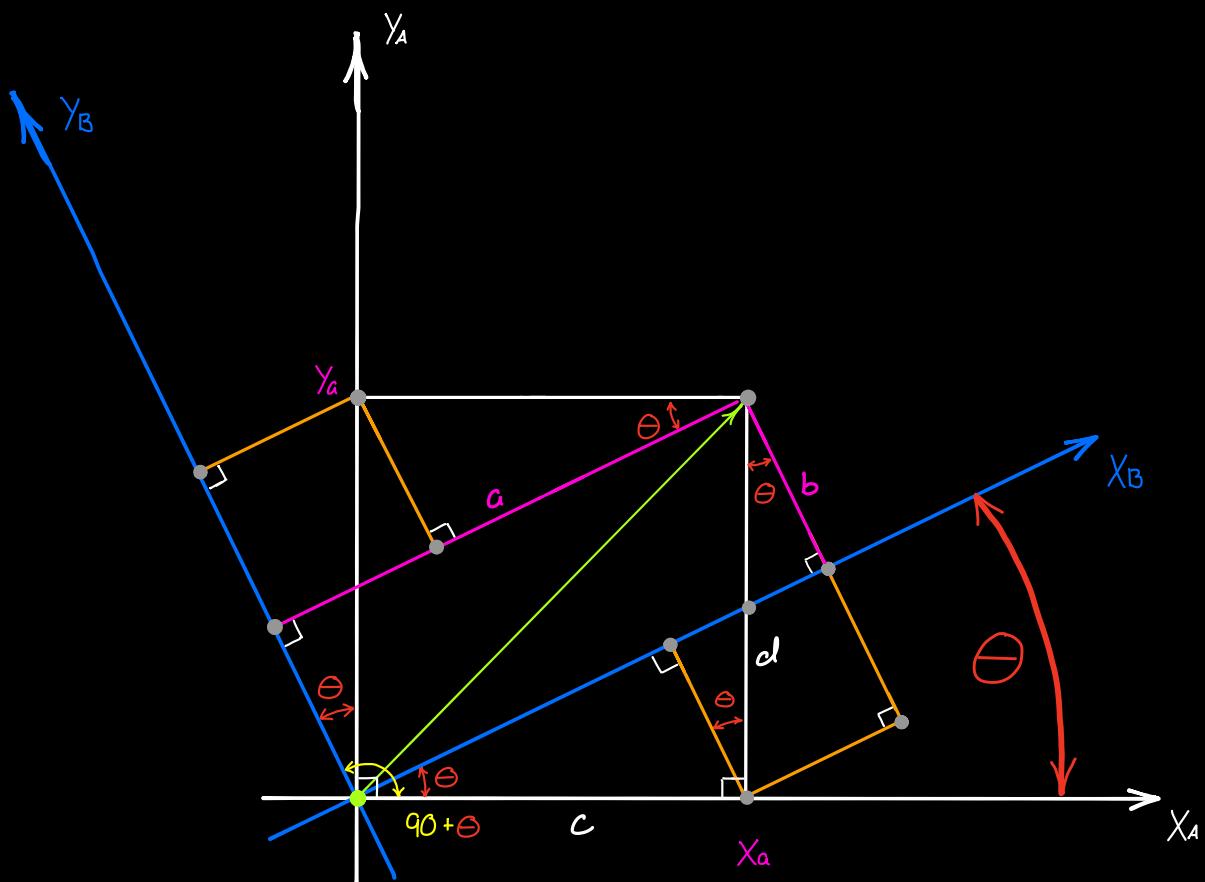
$$X_b = (X_a \cos \theta + Y_a \sin \theta) \\ Y_b = (-X_a \sin \theta + Y_a \cos \theta)$$

$$\begin{bmatrix} X_b \\ Y_b \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} X_a \\ Y_a \end{bmatrix}$$

Example:

$$\vec{v} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \theta = \frac{\pi}{6}$$

$$\begin{bmatrix} X_b \\ Y_b \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \cdot \frac{\sqrt{3}}{2} + 2 \cdot \frac{1}{2} \\ 3 \cdot -\frac{1}{2} + 2 \cdot \frac{\sqrt{3}}{2} \end{bmatrix} = \begin{bmatrix} 3.598 \\ 0.323 \end{bmatrix}$$



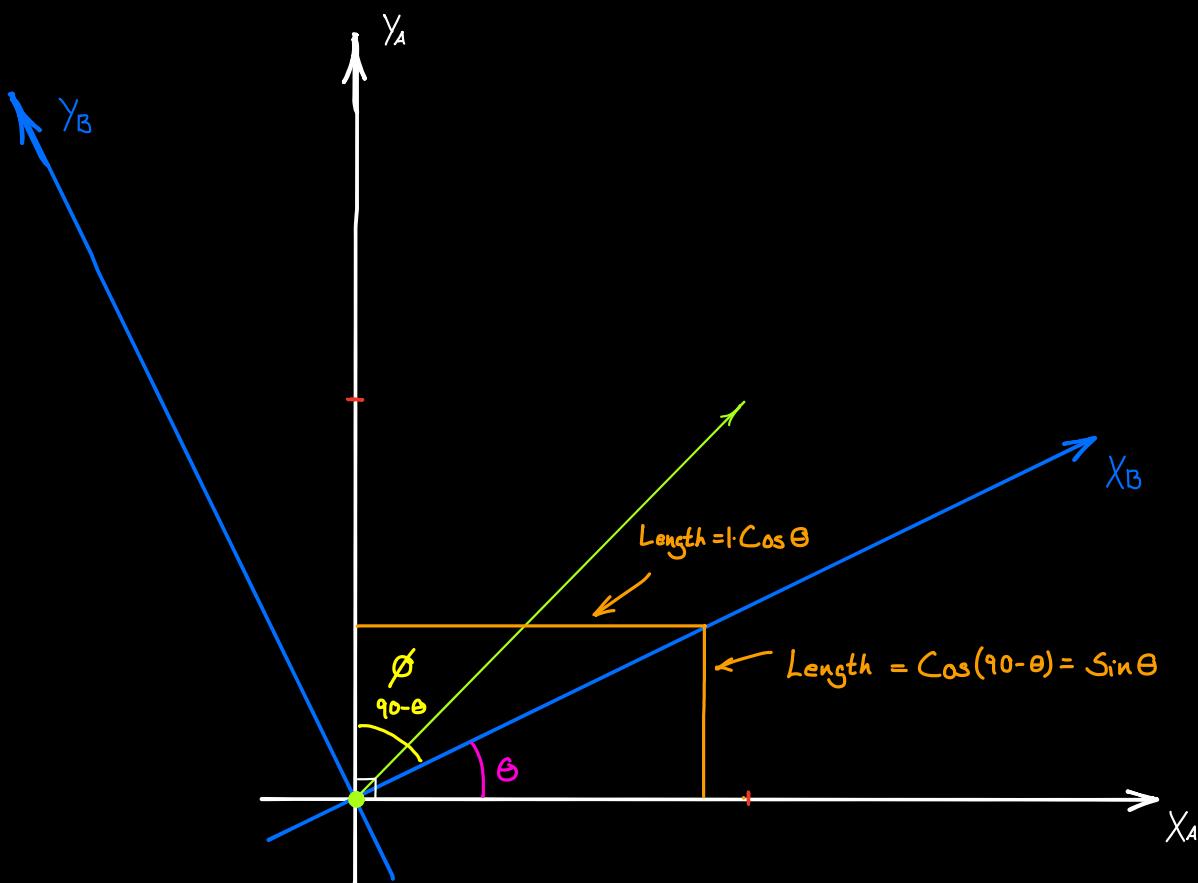
$$a^2 + b^2 = c^2 + d^2$$

$$\begin{aligned} i' &= i \cos \theta + j \sin \theta \\ j' &= j \cos \theta - i \sin \theta \end{aligned}$$

$$\vec{v} \cdot \vec{u} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

$$\begin{aligned} \vec{v} &= \cos \theta, \sin \theta, 0 \\ \vec{u} &= 1, 0, 0 \end{aligned} ; \|\vec{u}\| = 1$$

$$\frac{\vec{v} \cdot \vec{u}}{\|\vec{v}\| \|\vec{u}\|} = \cos \theta$$



$$\hat{x}_b = \cos\theta \hat{i} + \cos\phi \hat{j}$$

$$\cos(90 - \theta) = \sin\theta$$

$$\hat{y}_b = -\sin\theta \hat{i} + \cos\theta \hat{j}$$

$$\hat{i}' = \cos\theta \hat{i} + \sin\theta \hat{j} \rightarrow \text{slope} = \frac{\sin\theta}{\cos\theta}$$

$$\hat{x}_a = \hat{i} \uparrow + O \hat{j}$$

$$\hat{y}_a = O \hat{i} + \hat{i} \uparrow$$

slope at 90° = - recip. = -Cot

$$\begin{bmatrix} \hat{x}_b & \hat{x}_c \\ \hat{y}_b & \hat{y}_c \end{bmatrix} = \begin{bmatrix} \cos\theta \hat{i} & \sin\theta \hat{j} \\ -\sin\theta \hat{i} & \cos\theta \hat{j} \end{bmatrix} = \begin{bmatrix} \hat{i} & \hat{j} \\ \hat{x}_a & \hat{y}_a \end{bmatrix}$$